

## WHAT IS CLAIMED IS:

1. A stereo image measuring device comprising:

5 a setting unit for setting, regarding a stereo image including at least three or more points of measurement having position data thereof obtained, at least a part of the points of measurement as division points, and then setting a search area based on at least three division points selected from a plurality of the set division points;

10 an arithmetic operation unit for executing correlation processing for images of search areas corresponding to each other on the stereo image based on the search area set by the setting unit; and

a measuring unit for measuring a coordinate of a point in a given position from a result of the correlation executed by the arithmetic operation unit.

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2. The stereo image measuring device according to claim 1, wherein the setting unit assumes that three division points selected from the obtained division points form a division triangle, and sets a search area based on the division triangle.

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3. The stereo image measuring device according to claim 1, wherein the setting unit sets, in each stereo image, an inclusion square including a triangle composed of three adjacent points selected from the obtained division points, alternatively from points of measurement, as a  
25 search area.

4. The stereo image measuring device according to claim 1,

wherein

the setting unit selects points of measurement in an area where detailed division is required as new division points according to the result of the correlation processing executed by the arithmetic operation unit, and  
5 then sets new search areas on the stereo image, and

the arithmetic operation unit executes correlation processing for images of the new search areas.

5. The stereo image measuring device according to claim 1,  
10 wherein the setting unit sets a reference data block in the search areas of one image of the stereo image, and a search data block in the search areas of the other image of the same, and then sets a position, alternatively a moving step of each data block according to a distance from the division point.

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6. The stereo image measuring device according to claim 1,  
wherein the setting unit sets a reference data block in the search areas of one image of the stereo image, and a search data block in the search areas of the other image of the same, and then sets a size of each data block  
20 according to a distance from the division point.

7. The stereo image measuring device according to claim 1,  
wherein the setting unit sets a reference data block in the search areas of one image of the stereo image, and a search data block in the search areas of  
25 the other image of the same, sets a plurality of data blocks having different sizes in the vicinity of the division point, obtains a result of correlation, and then decides a size of each data block according to the result of the

correlation.

8. The stereo image measuring device according to claim 1,  
wherein the setting unit sets a reference data block in the search areas of  
5 one image of the stereo image, and a search data block in the search areas of  
the other image of the same, and decides a size of each data block according  
to a size of each search area.

9. The stereo image measuring device according to claim 1,  
10 wherein

the setting unit sets a data block based on the set search area, the  
data block being smaller than the search area, and

the arithmetic operation unit sets a block equivalent to a data block  
of one image of the stereo image as a template, scans the other image of the  
15 stereo image in a vertical position similar to that of the template, and  
searches a data block corresponding to the template based on a calculated  
correlation value.

10. The stereo image measuring device according to claim 1,  
20 further comprising a display unit for displaying the stereo image in a  
graphic manner,

wherein other division points are selected according to an area  
determined to need additional measurement based on graphic displaying of  
the display unit, and the search area setting unit sets new search areas, and  
25 the arithmetic operation unit executes correlation processing for images of  
the new search areas.

11. A stereo image measuring device comprising:

a setting unit for setting, regarding a stereo image including at least three or more points of measurement having position data thereof obtained, at least a part of the points of measurement as division points, and then  
5 setting a search area based on at least three division points selected from a plurality of the set division points;

an arithmetic operation unit for executing correlation processing for images of search areas corresponding to each other on the stereo image based on the search area set by the setting unit; and

10 a measuring unit for measuring a coordinate of a point in a given position based on a result of the correlation executed by the arithmetic operation unit,

wherein the arithmetic operation unit prepares information regarding an area of measurement where a new point of measurement is  
15 required, according to the result of the correlation processing.

12. The stereo image measuring device according to claim 11, further comprising a display unit for displaying a stereo image,

wherein the display unit executes predetermined displaying for an  
20 area where additional measurement is required according to the information of the area of measurement prepared by the arithmetic operation unit.

13. The stereo image measuring device according to claim 12,  
25 wherein

the display unit displays the area where additional measurement on is required the stereo image in a graphic manner, and

position data is received when the position data of the new point of measurement in the area is measured by an external survey instrument based on the graphic displaying of the display unit.

5           14. The stereo image measuring device according to claim 11, wherein the measuring unit outputs the information of the area of measurement prepared by the arithmetic operation unit to an auto-tracking total station, causes the total station to measure a position of a new point of measurement in an area indicated by the area data, and then receives the  
10 measured position data.

          15. The stereo image measuring device according to claim 11, wherein

          the setting unit selects points of measurement in an area where  
15 detailed division is required as new division points according to the information of the area of measurement prepared by the arithmetic operation unit, and then sets new search areas on the stereo image, and

          the arithmetic operation unit executes correlation processing for images of the new search areas.

20           16. The stereo image measuring device according to claim 11, wherein the setting unit sets, in each stereo image, an inclusion square including a triangle composed of three adjacent points selected from the obtained division points, alternatively from points of measurement, as a  
25 search area.

          17. The stereo image measuring device according to claim 11,

wherein the setting unit sets a reference data block in the search area of one image of the stereo image, and a search data block in the other of the search areas of the other image of the same, and then sets a position, alternatively a moving step of each data block according to a distance from the division  
5 point.

18. The stereo image measuring device according to claim 11,  
wherein the setting unit sets a reference data block in the search areas of one image of the stereo image, and a search data block in the search areas of  
10 the other image of the same, and then sets a size of each data block according to a distance from the division point.

19. The stereo image measuring device according to claim 11,  
wherein the setting unit sets a reference data block in the search areas of  
15 one image of the stereo image, and a search data block in the search areas of the other image of the same, sets a plurality of data blocks having different sizes in the vicinity of the division point, obtains a result of correlation, and decides a size of each data block according to the result of the correlation.

20 20. The stereo image measuring device according to claim 11,  
wherein the setting unit sets a reference data block in the search areas of one image of the stereo image, and a search data block in the search areas of the other image of the same, and then decides a size of each data block according to a size of each search area.

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21. The stereo image measuring device according to claim 11,  
wherein

the setting unit sets a data block based on the set search area, the data block being smaller than the search area, and

the arithmetic operation unit sets a block equivalent to the data block of one image of the stereo image as a template, scans the other image  
5 of the stereo image in a vertical position similar to that of the template, and searches a data block corresponding to the template based on a calculated correlation value.

22. A stereo image measuring method comprising:

10 a setting step of setting, regarding a stereo image including at least three or more points of measurement having position data thereof obtained, at least a part of the points of measurement as division points, and then setting a search area based on at least three division points selected from a plurality of the set division points;

15 an arithmetic operation step of executing correlation processing for images of search areas corresponding to each other on the stereo image based on the search area set by the setting unit; and

a measuring step of measuring a coordinate of a point in a given position from a result of the correlation executed by the arithmetic operation  
20 unit.

23. The stereo image measuring method according to claim 22, wherein in the setting step, it is assumed that three division points selected from the obtained division points form a division triangle, and a search area  
25 is set based on the division triangle.

24. The stereo image measuring method according to claim 22,

wherein in the setting step, an inclusion square including a triangle composed of three adjacent points selected the obtained division points, alternatively from points of measurement, is set as a search area in each stereo image.

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25. The stereo image measuring method according to claim 22, wherein

in the setting step, points of measurement in an area where detailed division is required are selected as new division points according to the  
10 result of the correlation processing executed in the arithmetic operation unit, and then new search areas are set on the stereo image, and

in the arithmetic operation unit, correlation processing is executed for images of the new search areas.

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26. The stereo image measuring method according to claim 22, wherein in the arithmetic operation step, information is prepared regarding an area of measurement where a new point of measurement is required according to the result of the correlation processing.

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27. The stereo image measuring method according to claim 26, further comprising a displaying step for displaying the stereo image,

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wherein in the displaying step, predetermined displaying is executed for an area where additional measurement is required according to the information of the area of measurement prepared in the arithmetic  
operation step.

28. The stereo image measuring method according to claim 26,



wherein

in the displaying step, the area where additional measurement is required is displayed in a graphic manner, and

when position data of a new point of measurement in the area is  
5 measured by an external survey instrument based on the graphic displaying  
executed in the displaying step, the position data is received.

29. The stereo image measuring method according to claim 26,  
wherein in the measuring step, the information of the area of measurement  
10 prepared in the arithmetic operation unit is outputted to an auto-tracking  
total station, the total station is caused to measure a position of a new point  
of measurement in an area indicated by the area data, and then measured  
position data is received.